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Problem 2.41 continued:

Because the initial values can be arbitrary, the

general form of the

solution is $y(t) = e^{-t} + A_1 \sin t + A_2 \cos t$ (1) 2

This form can be used to

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obtain a solution for cases where $y(t)$ or $\dot{y}(t)$ are specified at points other than $t = 0$.

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1.26 Only the semilog
plot of the data gives
something close to a
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best described by an exponential function $y = b(10)^{mx}$ where y is the temperature in degrees C and x is the time in seconds.

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2.3 a) $Z x^3 dx = \frac{1}{4} 5x^4 + C$
 $0 dt = t Z x^3 dx = \frac{1}{4} 5x^4 + C$
 $5 \ln |x| + C = \frac{1}{4} 5x^4 + C$
 $\arctanh \frac{3}{5} = \frac{1}{4} 5x^4 + C$ Let

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$C = \operatorname{arctanh} \frac{3}{5}$

Solve for x to obtain $x = \frac{p}{5} \tanh(5p/5t + C)$

b) $\int x$

$10 dx = 36 + 4x^2 \int_{t=0}^t dt =$

t

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The solution is $x(t) =$
 $-0.25e^{-2t} + 0.25 +$
 $0.5t - e^{-3t} + 2e^{-5t}$
 $[r,p,k] =$

$\text{residue}([4,3],[1,6,34,0])$

The result is $r = [-0.0441$
 $- 0.3735i, -0.0441 +$
 $0.3735i, 0.0882], p =$
 $[-3.0000 + 5.0000i,$
 $-3.0000 - 5.0000i, 0],$ and
 $k = []$. The solution is

$x(t) = (-0.0441 -$
 $0.3735j)e^{(-3+5j)t} +$
 $(-0.0441 +$

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$0.3735j)e^{(-3 - 5j)t} +$
0.0882 The solution is
 $x(t) = 2e^{-3t} (-0.0441$
 $\cos 5t + 0.3735 \sin 5t) +$
0.0882 (continued on the
next page)

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The characteristic
equation derived earlier
becomes $2 \quad 2 \quad 2+3$
 $+1=0.01 \quad 2+0.3 \quad +1=0$

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whose roots are
 $= -26.18$ and $= -3.82$.
The dominant time
constant is $1/3.82=0.262$,
and thus we would
expect the steady-state
response to be reached in
about $4(0.262)=1.04$ s.
The scope plot confirms
this. 16.

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with mathematical
modeling and analysis of
devices and processes for
the purpose of
understanding their time-
dependent behavior.
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such as Newtonian
dynamics and electrical
circuit theory, also deal

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interconnected elements
often require a control
system to work properly,
control system design is a
major application area in
system dynamics.

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electromechanical
devices, electrohydraulic
devices, and fluid-
thermal processes.

Because systems of
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of motion with the pressures p_1 and p_2 as inputs. ” is broken down into a number of easy to

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